

Sparse finite element methods

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Based on joint work with
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Some pointers to the literature

Survey article:



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Journal & conference papers:

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Journal & conference papers [continued]:

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H. Yserentant. Sparse grid spaces for the numerical solution of the electronic Schrödinger equation. *Numerische Mathematik*, 101(2):381–389, 2005.

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G. Widmer, R. Hiptmair and C. Schwab. Sparse Adaptive Finite Elements for Radiative Transfer. *SAM Technical Report*. ETH Zürich, January 2007.

C. Schwab, E. Süli, R.-A. Todor. Sparse finite element approximation of high-dimensional transport-dominated diffusion problems. *M²AN* (Submitted, 2007).

Scientific motivation

High-dimensional partial differential equations arise in:

- Stochastic analysis
- Mathematical finance
- Statistical physics
 - ▶ Kinetic theory of gases and plasma (Boltzmann and Vlasov equations)
 - ▶ Kinetic theory of dilute polymers (degenerate Fokker–Planck equations)
 - ▶ Radiative heat transfer equations
- Quantum chemistry: Schrödinger equation

Example 1: Schrödinger equation

High-dimensional PDEs give rise to a major computational challenge.

“One hundred grid points represent a fair resolution for two-point boundary value problems in one space dimension. To obtain the same resolution in three space dimensions, already a million grid points are needed.

The number increases to the unthinkable 10^{60} grid points for equations in 30 dimensions, as in the electronic Schrödinger equation for small molecules



such as

water

or

ammonia.”

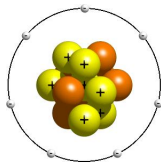
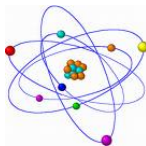
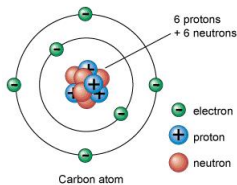


H. Yserentant: Sparse grid spaces for the numerical solution of the electronic Schrödinger equation. Numer. Math. (2005).

Physically admissible eigenfunctions of the electronic Schrödinger operator

$$H = -\frac{1}{2} \sum_{i=1}^N \Delta_i - \sum_{i=1}^N \sum_{v=1}^K \frac{Z_v}{|x_i - a_v|} + \frac{1}{2} \sum_{\substack{i,j=1 \\ i \neq j}}^N \frac{1}{|x_i - x_j|},$$

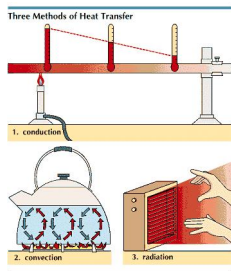
where $x_1, \dots, x_N \in \mathbb{R}^3$ are the co-ordinates of N given electrons, a_v are the co-ordinates of K nuclei, and Z_v are the charges, are antisymmetric under the exchange of electron coordinates x_i and x_j with indices i and j . (Pauli).



Example 2: Radiative heat transfer equation

Consider the monochromatic radiative heat transfer eq. on a bounded Lipschitz domain $D \subset \mathbb{R}^d$, $d = 2, 3$, without scattering.

We identify a direction s with a point on the unit sphere \mathbb{S}^d and seek the intensity $u(x, s)$:



$$\begin{aligned} s \cdot \nabla_x u(x, s) + \kappa(x)u(x, s) &= \kappa(x)f(x), & (x, s) \in D \times \mathbb{S}^d, \\ u(x, s) &= g(x, s), & x \in \partial D, \quad s \cdot n(x) < 0, \end{aligned}$$

- $n(x)$ is the unit outer normal to the boundary at $x \in \partial D$,
- $\kappa \geq 0$ is the absorption coefficient,
- $f \geq 0$ is the black-body intensity and $g \geq 0$ is the wall emission.

⇒ PDE in $d + (d - 1) = 2d - 1$ dimensions.

Example 3: Kolmogorov–Fokker–Planck equations

Consider the (Itô) stochastic differential equation:

$$dX_t = b(X_t) dt + \sigma(X_t) dW_t, \quad X_0 = X.$$

Here:

- $W = (W^1, \dots, W^k)$ is a Wiener process w.r.t. a filtration $\{\mathcal{F}_t, t \geq 0\}$;
- $\sigma : \mathbb{R}^d \rightarrow \mathbb{R}^{d \times k}$ is Lipschitz continuous \rightsquigarrow dispersion/volatility;
- $b : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is Lipschitz continuous \rightsquigarrow drift.

Define:

- $a := \sigma \sigma^\top : \mathbb{R}^d \rightarrow \mathbb{R}^{d \times d}$ \rightsquigarrow diffusion matrix.

Backward Kolmogorov (Fokker–Planck) equation

Theorem

Let the random variable X_t have a density function $(x, t) \mapsto \psi(x, t)$ of class $C^{2,1}(\mathbb{R}^d \times [0, \infty))$, and let $X_0 = X$ be a square-integrable random variable that is \mathcal{F}_0 -measurable with density function $\psi_0 \in C^2(\mathbb{R}^d)$. Then,

$$\partial_t \psi + \sum_{j=1}^d \frac{\partial}{\partial x_j} (b_j \psi) = \frac{1}{2} \sum_{i,j=1}^d \frac{\partial^2}{\partial x_i \partial x_j} (a_{ij} \psi)$$

in $\mathbb{R}^d \times (0, \infty)$ and $\psi(x, 0) = \psi_0(x)$ for $x \in \mathbb{R}^d$.

$$a(x) = \sigma(x)\sigma^\top(x) \geq 0$$

Computational challenges:

- PDE non-self-adjoint, transport/drift-dominated, perhaps degenerate
- PDE high-dimensional

Example 4: non-Newtonian fluids

Find $u : \Omega \times (0, \infty) \mapsto \mathbb{R}^3$ and $p : \Omega \times (0, \infty) \mapsto \mathbb{R}$ such that

$$\begin{aligned} \partial_t u + (u \cdot \nabla_x) u - \nu \Delta_x u + \nabla_x p &= f + \nabla_x \cdot \tau && \text{in } \Omega \times (0, \infty), \\ \nabla_x \cdot u &= 0 && \text{in } \Omega \times (0, \infty), \\ u &= 0 && \text{on } \partial\Omega \times (0, \infty), \\ u(x, 0) &= u_0(x) && x \in \Omega; \end{aligned}$$

where $\tau(x, t)$ is the symmetric *extra stress tensor*.

Example

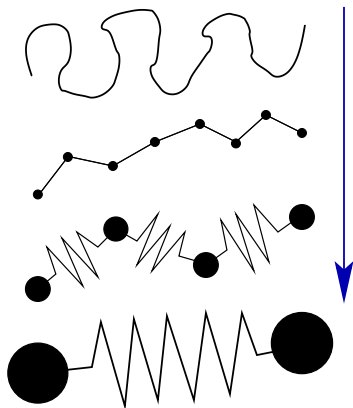
- Algebraic models: $\tau = F(\nabla u)$ Quasi-Newtonian
- Differential models: $\partial_t \tau + u \cdot \nabla \tau = F(\tau, \nabla u)$ Oldroyd-B

Non-Newtonian fluids

Gareth McKinley's Non-Newtonian Fluid Dynamics Group, MIT

Jonathan Rothstein's Non-Newtonian Fluids Dynamics Lab, University of Massachusetts

Kinetic polymer models: Kramers chain \rightarrow dumbbell



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The viscosity of macromolecules in a streaming fluid. *Physica*, 11, 1944.



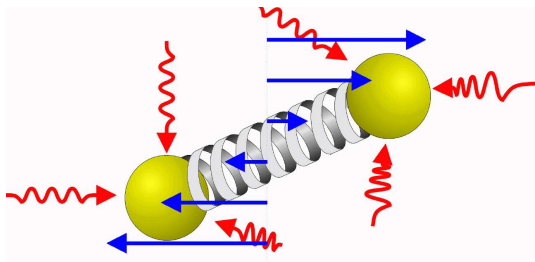
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Dumbbell model



$$\begin{cases} dX_t = u(X_t, t) dt \\ dQ_t = \left(\nabla_X u(X_t, t) Q_t - \frac{1}{2\lambda} F(Q_t) \right) dt + \frac{1}{\sqrt{\lambda}} dW_t ; \end{cases}$$

W

$\lambda = \xi / (4H)$

ξ

$F(Q) := U'(\frac{1}{2}|q|^2)q$

vector of independent scalar Wiener processes;
characterises the elastic property of the fluid;
drag coefficient and H the spring stiffness;
elastic force acting on the chain due to elongation.

$(x, q, t) \in \mathbb{R}^6 \times \mathbb{R}_{\geq 0} \mapsto \Psi(x, q, t) \in \mathbb{R}_{\geq 0}$ is a *probability density function*:

$$\begin{aligned} \partial_t \Psi + (u \cdot \nabla_x) \Psi + \nabla_q \cdot \left((\nabla_x u) q \Psi - \frac{1}{2\lambda} U' q \Psi \right) &= \frac{1}{2\lambda} \Delta_q \Psi \quad \text{in } \Omega \times D \times (0, \infty), \\ \Psi &= 0 \quad \text{on } (\Omega \times \partial D) \times (0, \infty), \\ \Psi(x, q, 0) &= \Psi_0(x, q) \quad \text{for } (x, q) \in \Omega \times D. \end{aligned}$$

Kramers expression for extra stress tensor:

$$\tau(x, t) = k\mu \int_D \Psi(x, q, t) \left[U' \left(\frac{1}{2} |q|^2 \right) q q^\top - \rho(x, t) I \right] dq, \quad k, \mu > 0.$$

Example: FENE (finitely extendible nonlinear elastic) potential:

$$U(q) = -\frac{b}{2} \ln \left(1 - \frac{|q|^2}{b} \right), \quad U'(q) = \frac{1}{1 - \frac{|q|^2}{b}}, \quad q \in D = \{q : |q| < \sqrt{b}\}.$$

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Outline

- PDEs with non-negative characteristic form
- Weak and stabilized variational formulations
- Univariate hierarchical spaces
- Multidimensional sparse tensor product spaces
- Approximability from sparse tensor product spaces
- Stability and convergence of the sparse stabilized FEM

Based on:



C. Schwab, E. Süli, R.-A. Todor: Sparse finite element approximation of high-dimensional transport-dominated diffusion problems. *M²AN* (Submitted, 2007).

1. PDEs with non-negative characteristic form

$$\mathcal{L}u := -a : \nabla \nabla u + b \cdot \nabla u + cu = f(x), \quad x \in \Omega, \quad + \text{BCs},$$

$$\Omega = (0, 1)^d \quad \text{and} \quad d \gg 1.$$

Assume that $c > 0$, $b \in \mathbb{R}^d$, $a \in \mathbb{R}^{d \times d}$, with $a = a^\top \geq 0$.

Special cases:

- When a is positive definite, the PDE is *elliptic*;
- When $a = 0$ and $b \neq 0$, the PDE is first-order *hyperbolic*;
- When

$$a = \begin{pmatrix} \alpha & 0 \\ 0 & 0 \end{pmatrix}, \quad \text{with } \alpha \in \mathbb{R}^{(d-1) \times (d-1)}, \quad \alpha = \alpha^\top > 0$$

and $b = (0, \dots, 0, 1)^\top \in \mathbb{R}^d$, the PDE is *parabolic*.

2. Weak and stabilized variational formulations

Find $u : \Omega \subset \mathbb{R}^d \rightarrow \mathbb{R}$:

$$\begin{aligned} \mathcal{L}u &\equiv -\nabla \cdot (a\nabla u) + \nabla \cdot (bu) + cu = f \quad \text{in } \Omega, \\ u &= 0 \quad \text{on } \Gamma_D \cup \Gamma_-, \quad n \cdot (a\nabla u) = 0 \quad \text{on } \Gamma_N. \end{aligned}$$

$$\zeta^\top a(x) \zeta \geq 0 \quad \forall \zeta \in \mathbb{R}^d, \quad \text{a.e. } x \in \bar{\Omega}.$$

$$\begin{aligned} \Gamma_0 &\equiv \Gamma_D \cup \Gamma_N = \left\{ x \in \Gamma : n(x)^\top a(x) n(x) > 0 \right\} && \text{(Elliptic boundary)} \\ \Gamma_- &= \left\{ x \in \Gamma \setminus \Gamma_0 : b(x) \cdot n(x) < 0 \right\} && \text{(Hyperbolic inflow)} \\ \Gamma_+ &= \left\{ x \in \Gamma \setminus \Gamma_0 : b(x) \cdot n(x) \geq 0 \right\} && \text{(Hyperbolic outflow)} \end{aligned}$$

Fichera function: $x \mapsto b(x) \cdot n(x)$ defined on Γ .

Suppose that $v \in H^1(\Omega)$ with $v|_{\Gamma_D} = 0$. Via formal integration by parts:

$$\begin{aligned} \int_{\Omega} a \nabla u \cdot \nabla v \, dx - \int_{\Omega} b u \cdot \nabla v \, dx + \int_{\Omega} c u v \, dx \\ - \int_{\Gamma} (a \nabla u \cdot n) v \, ds + \int_{\Gamma} (b \cdot n) u v \, ds = \int_{\Omega} f v \, dx. \end{aligned}$$

$$\begin{aligned} \int_{\Gamma} (b \cdot n) u v \, ds &= \int_{\Gamma_N \cup \Gamma_+} (b \cdot n) u v \, ds, \\ \int_{\Gamma} (a \nabla u \cdot n) v \, ds &= \int_{\Gamma \setminus \Gamma_0} ((\nabla u)^\top a n) v \, ds = 0, \end{aligned}$$

since $n^\top a n = 0$ on $\Gamma \setminus \Gamma_0$ and $a = a^\top \geq 0$ implies that $a n = 0$ on $\Gamma \setminus \Gamma_0$.

$$\mathcal{V} := \{v \in H^1(\Omega) : v|_{\Gamma_D} = 0\}, \quad \langle w, v \rangle_\gamma = \int_\gamma |b \cdot n| v w \, ds, \quad \gamma \subset \Gamma,$$

$\mathcal{H} :=$ closure of \mathcal{V} in the norm induced by

$$(w, v)_\mathcal{H} := (a \nabla w, \nabla v) + (w, v) + \langle w, v \rangle_{\Gamma_N \cup \Gamma_- \cup \Gamma_+}.$$

Weak formulation: Find $u \in \mathcal{H}$ such that

$$B(u, v) = \ell(v) \quad \forall v \in \mathcal{V},$$

where

$$\begin{aligned} B(u, v) &= (a \nabla u, \nabla v) - (u, b \cdot \nabla v) + (cu, v) + \langle u, v \rangle_{\Gamma_N \cup \Gamma_+}, \\ \ell(v) &= (f, v). \end{aligned}$$

Existence of weak solutions:



Oleřnik & Radkevič (1973)

A special case: $\Omega = (0, 1)^d$

Lemma

Each of the sets Γ_0 , Γ_+ , Γ_- is the union of $(d-1)$ -dimensional open faces of Ω . Moreover, each pair of opposite $(d-1)$ -dimensional faces of Ω is contained either in the elliptic part Γ_0 of Γ or its complement $\Gamma_- \cup \Gamma_+$, the hyperbolic part of Γ .

We shall assume henceforth that $\Gamma_N = \emptyset$ (i.e. that $\Gamma_0 = \Gamma_D$).

Weak formulation: Find $u \in \mathcal{H}$ such that

$$B(u, v) = \ell(v) \quad \forall v \in \mathcal{V} = \{v \in H^1(\Omega) : v|_{\Gamma_0} = 0\},$$

where

$$\begin{aligned} B(u, v) &= (a \nabla u, \nabla v) - (u, b \cdot \nabla v) + (cu, v) + \langle u, v \rangle_{\Gamma_+}, \\ \ell(v) &= (f, v). \end{aligned}$$

Remarks

$u|_{\Gamma_0} = 0$ is imposed **strongly**, through the definition of $\mathcal{V} \subset \mathcal{H}$,
 $u|_{\Gamma_-} = 0$ is imposed **weakly**, through the definition of $B(\cdot, \cdot)$.

Hence,

$$\bigotimes_{i=1}^d \mathbf{H}_{(0)}^1(0, 1) := \mathbf{H}_{(0)}^1(0, 1) \otimes \cdots \otimes \mathbf{H}_{(0)}^1(0, 1) \subset \mathcal{H},$$

where the i th component in the tensor-product is

$$\mathbf{H}_{(0)}^1(0, 1) := \begin{cases} \mathbf{H}_0^1(0, 1) & \text{if } \mathbf{O}x_i \text{ is an } \textit{elliptic} \text{ co-ordinate direction,} \\ \mathbf{H}^1(0, 1) & \text{if } \mathbf{O}x_i \text{ is a } \textit{hyperbolic} \text{ co-ordinate direction.} \end{cases}$$

We wish to construct a Galerkin finite element approximation to the boundary-value problem using finite-dimensional subspaces of \mathcal{H} that have *analogous* tensor-product structure.

Stabilization

$$\begin{aligned} -\nabla \cdot (a \nabla u) + \nabla \cdot (bu) + cu &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \Gamma_D \cup \Gamma_-. \end{aligned}$$

Perturbed weak formulation: Find $u \in \mathcal{H}$ such that

$$B_\delta(u, v) = \ell_\delta(v) \quad \forall v \in \mathcal{V},$$

where

$$\begin{aligned} B_\delta(u, v) &= B(u, v) + \sum_{\alpha \in \mathcal{T}} \delta_\alpha (-\nabla \cdot (a \nabla u) + \nabla \cdot (bu) + cu, \mathbf{b} \cdot \nabla v)_\alpha \\ \ell_\delta(v) &= \ell(v) + \sum_{\alpha \in \mathcal{T}} \delta_\alpha (f, \mathbf{b} \cdot \nabla v)_\alpha, \end{aligned}$$

$\delta_\alpha \geq 0$ — stabilization parameter.

Stabilized finite element method

Find $u_{\text{SD}} \in V_{hp} \subset \mathcal{V}$ such that

$$B_{\delta}(u_{\text{SD}}, v) = \ell_{\delta}(v) \quad \forall v \in V_{hp}.$$

Streamline-diffusion norm:

$$\| \| u \| \|_{\text{SD}} = \left(\|\sqrt{a} \nabla u\|_{L^2(\Omega)}^2 + \|u\|_{L^2(\Omega)}^2 + \|u\|_{\Gamma_+ \cup \Gamma_-}^2 + \sum_{\alpha \in \mathcal{T}} \delta_{\alpha} \|b \cdot \nabla u\|_{L^2(\alpha)}^2 \right)^{\frac{1}{2}}$$

Coercivity and stability: There exist $\delta_0 > 0$, $c_0 > 0$ s.t., for all $\delta \in [0, \delta_0]$,

$$B_{\delta}(v, v) \geq c_0 \| \| v \| \|_{\text{SD}}^2 \quad \forall v \in V_{hp}, \quad \| \| u_{\text{SD}} \| \|_{\text{SD}} \leq \frac{1}{c_0} \left(\sum_{\alpha \in \mathcal{T}} (1 + \delta_{\alpha}) \|f\|_{L^2(\alpha)}^2 \right)^{\frac{1}{2}}.$$

Key observation: for all $v \in V_{hp}$

$$B_{\delta}(v, v) \geq \int_{\Omega} |\sqrt{a} \nabla v|^2 dx + \int_{\Omega} (c + \frac{1}{2} \nabla \cdot b) |v|^2 dx + \frac{1}{2} \int_{\Gamma_N \cup \Gamma_+ \cup \Gamma_-} |b \cdot n| |u|^2 ds \\ + \frac{1}{2} \sum_{\alpha \in \mathcal{T}} \delta_{\alpha} \int_{\alpha} |b \cdot \nabla v|^2 dx - \sum_{\alpha \in \mathcal{T}} \delta_{\alpha} \int_{\alpha} [(c - \nabla \cdot b)^2 |v|^2 + |\nabla \cdot (a \nabla v)|^2] dx.$$

Norm-equivalence in finite-dimensional normed linear spaces \Rightarrow


Coercivity: There exists $c_0 = c_0(c_*)$ such that

$$B_{\delta}(v, v) \geq c_0 \|v\|_{SD}^2 \quad \forall v \in V_{hp}.$$

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 Baiocchi, Brezzi, Franca (1993), Brezzi & Russo (1994) \rightarrow RFB/multiscale FEMs

 Brezzi, Hughes, Marini & Süli (1989), Brezzi, Marini & Süli (2000)

A brief interlude

Let B_p^d denote the d -dimensional ball of radius L in \mathbb{R}^d in the ℓ_p norm. Clearly, $B_1^d \subset B_2^d \subset B_\infty^d$.

Question: What are the volumes of the three balls?

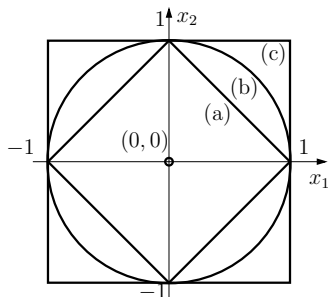


Figure 1: ‘Unit circles’ in the linear space \mathbb{R}^2 with respect to three vector norms: (a) the 1-norm; (b) the 2-norm; (c) the ∞ -norm.

Answer:

$$\begin{aligned}\text{Vol}(B_\infty^d) &= (2L)^d, \\ \text{Vol}(B_2^d) &= \frac{\pi^{d/2} L^d}{\Gamma(d/2 + 1)}, \\ \text{Vol}(B_1^d) &= 2^d \frac{\prod_{k=1}^d L}{d!}.\end{aligned}$$

Note, in particular, that

$$\frac{\text{Vol}(B_1^d)}{\text{Vol}(B_\infty^d)} = \frac{1}{d!}.$$

If $d = 30$, then $1/d! = 3.77 \cdot 10^{-33}$.

If $d = 100$, then $1/d! = 1.07 \cdot 10^{-158}$.

3. Univariate hierarchical spaces

$\mathcal{T}^\ell :=$ uniform mesh of spacing $h_\ell = 2^{-\ell}$, $\ell \geq 0$, on $[0, 1]$,

$\mathcal{V}^{\ell,p} := \{\text{all continuous p.w. polynomials of degree } p \text{ defined on } \mathcal{T}^\ell\}$,

$\mathcal{V}_0^{\ell,p} := \mathcal{V}^{\ell,p} \cap \mathbf{H}_0^1(0, 1)$.

The families of spaces $\{\mathcal{V}^{\ell,p}\}_{\ell \geq 0}$ and $\{\mathcal{V}_0^{\ell,p}\}_{\ell \geq 0}$ are nested, i.e.,

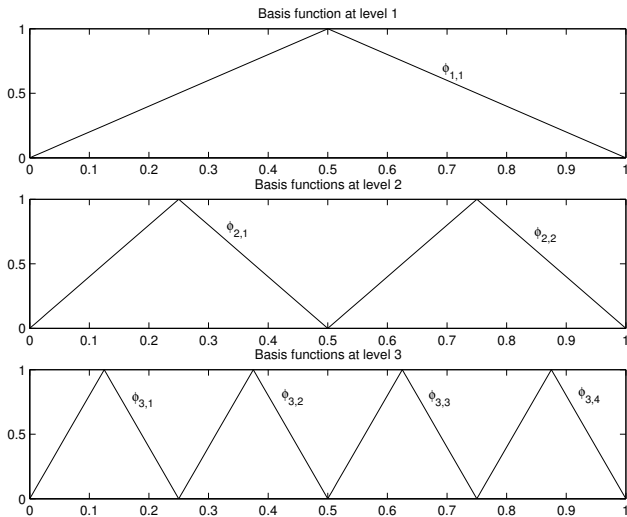
$$\mathcal{V}^{0,p} \subsetneq \mathcal{V}^{1,p} \subsetneq \mathcal{V}^{2,p} \subsetneq \dots \subsetneq \mathcal{V}^{\ell,p} \subsetneq \dots \subsetneq \mathbf{H}^1(0, 1),$$

and

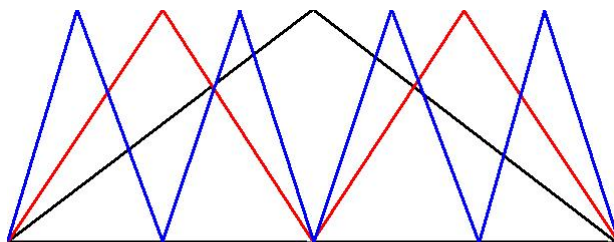
$$\mathcal{V}_0^{0,p} \subsetneq \mathcal{V}_0^{1,p} \subsetneq \mathcal{V}_0^{2,p} \subsetneq \dots \subsetneq \mathcal{V}_0^{\ell,p} \subsetneq \dots \subsetneq \mathbf{H}_0^1(0, 1).$$

Notation: $\mathcal{V}_{(0)}^{\ell,p}$ is $\mathcal{V}^{\ell,p}$ or $\mathcal{V}_0^{\ell,p}$, as the case may be.

Linear hierarchical basis: $p = 1$



Linear hierarchical basis: $p = 1$



Dimension of the space = $1 + 2 + \dots + 2^{L-1} = 2^L - 1$.

A basis-free definition of the subspaces

Consider

$$(P^{\ell,p}u)(x) := u(0) + \int_0^x (\Pi^{\ell,p-1}u')(\xi) d\xi, \quad P_0^{\ell,p} := P^{\ell,p}|_{\mathbf{H}_0^1(0,1)}.$$

Define

$$\mathcal{V}_{(0)}^{\ell,p} := P_{(0)}^{\ell,p} \mathbf{H}_{(0)}^1(0,1), \quad \ell \geq 0, \quad p \geq 1.$$

1-d approximation property: Let $u \in \mathbf{H}^{k+1}(0,1) \cap \mathbf{H}_{(0)}^1(0,1)$, $k \geq 1$; then,

$$\|\partial^s(u - P_{(0)}^{\ell,p})u\|_{\mathbf{L}^2(0,1)} \leq \left(\frac{h_\ell}{2}\right)^{t+1-s} \frac{1}{p^{1-s}} \sqrt{\frac{(p-t)!}{(p+t)!}} \|\partial^{t+1}u\|_{\mathbf{L}^2(0,1)},$$

where $1 \leq t \leq \min(p,k)$, $h_\ell = 2^{-\ell}$, $\ell \geq 0$, $p \geq 1$, $s \in \{0,1\}$.

Hierarchical decomposition

Incremental projectors:

$$Q_{(0)}^{\ell,p} := \begin{cases} P_{(0)}^{\ell,p} - P_{(0)}^{\ell-1,p}, & \ell \geq 1, \\ P_{(0)}^{0,p}, & \ell = 0. \end{cases}$$

Increment spaces:

$$\mathcal{W}_{(0)}^{\ell,p} := Q_{(0)}^{\ell,p} \mathbf{H}_{(0)}^1(0,1), \quad \ell \geq 0.$$

Now,

$$P_{(0)}^{L,p} = \sum_{\ell=0}^L Q_{(0)}^{\ell,p} \quad \Rightarrow \quad \mathcal{V}_{(0)}^{L,p} = \sum_{\ell=0}^L \mathcal{W}_{(0)}^{\ell,p}.$$

Proposition

Let X be a vector space; then, there exist nontrivial subspaces X_ℓ , $\ell = 0, \dots, L$, of X such that $X = \bigoplus_{\ell=0}^L X_\ell$ if, and only if, there are nonzero linear mappings $q_0, \dots, q_L : X \rightarrow X$ such that

$$(1) \sum_{\ell=0}^L q_\ell = \text{Id}_X;$$

$$(2) q_{\ell_1} \circ q_{\ell_2} = 0_X \text{ for all } \ell_1, \ell_2 \in \{0, \dots, L\}, \ell_1 \neq \ell_2.$$

Moreover, each q_ℓ is necessarily a projector and X_ℓ can be chosen to be $\text{Im}(q_\ell)$, $\ell = 0, \dots, L$.

Therefore,

$$Q_{(0)}^{\ell_1, P} Q_{(0)}^{\ell_2, P} = 0, \quad \ell_1 \neq \ell_2, \quad \implies \quad \mathcal{V}_{(0)}^{L, P} = \bigoplus_{\ell=0}^L \mathcal{W}_{(0)}^{\ell, P}.$$

4. Multidimensional sparse tensor-product spaces

Define

$$V_{(0)}^{L,p} := \mathcal{V}_{(0)}^{L,p} \otimes \dots \otimes \mathcal{V}_{(0)}^{L,p}.$$

Clearly,

$$V_{(0)}^{L,p} = \sum_{|\ell|_{\infty} \leq L} \mathcal{W}_{(0)}^{\ell_1,p} \otimes \dots \otimes \mathcal{W}_{(0)}^{\ell_d,p}.$$

Sparse tensor-product space

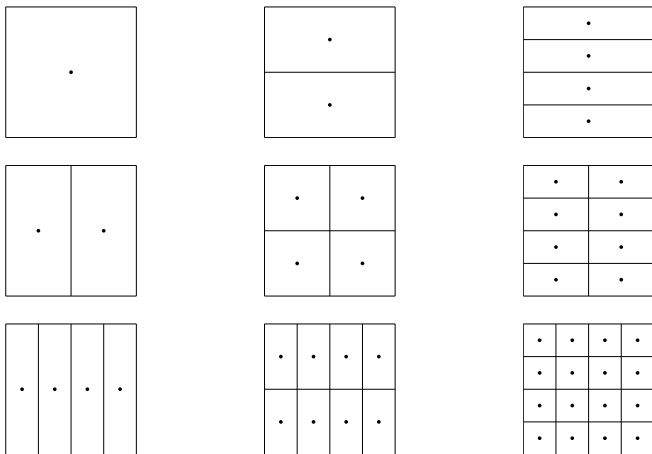
→ Babenko (1960), Smolyak (1963), Zenger (1990), Bungartz & Griebel (2004)

$$\hat{V}_{(0)}^{L,p} := \sum_{|\ell|_1 \leq L} \mathcal{W}_{(0)}^{\ell_1,p} \otimes \dots \otimes \mathcal{W}_{(0)}^{\ell_d,p}.$$

Number of DOFs (for p fixed):

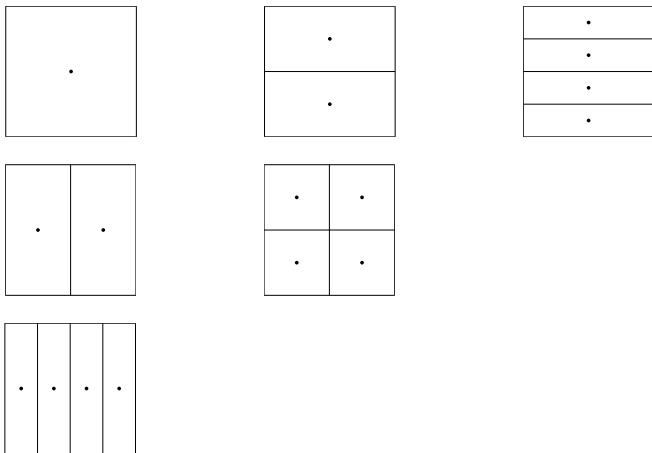
$$\dim V_{(0)}^{L,p} \asymp h_L^{-d}, \quad \dim \hat{V}_{(0)}^{L,p} \asymp h_L^{-1} |\log_2 h_L|^{d-1}.$$

Supports of basis functions in $V^{L,1}$



Dimension of the space = $(1 + 2 + \dots + 2^{L-1})^d = (2^L - 1)^d$.

Supports of basis functions in $\hat{V}^{L,1}$



$$\text{Dimension of the space} = \sum_{m=1}^L \binom{m+d-2}{d-1} 2^{m-1} \sim \frac{2^L L^{d-1}}{(d-1)!}.$$

Proof:

$$\mathcal{S}(m, k, d) := \{\ell \in \mathbb{N}^d : |\ell|_1 = m, |\ell|_\infty = k\}, \quad m, k \in \mathbb{N}.$$

Lemma

$$\begin{aligned} \mathcal{S}(m, k, d) &= \emptyset \quad \forall k > m, \\ \sum_{k=0}^{\infty} |\mathcal{S}(m, k, d)| &= \binom{m+d-1}{d-1}. \end{aligned}$$

$$\begin{aligned} \text{Dimension of the space} &= \sum_{\ell \in \mathbb{N}^d, |\ell|_1 \leq L-1} 2^{|\ell|_1} = \sum_{m=0}^{L-1} \sum_{\ell \in \mathbb{N}^d, |\ell|_1 = m} 2^m \\ &= \sum_{m=0}^{L-1} 2^m \sum_{k=0}^{\infty} \sum_{\ell \in \mathbb{N}^d, |\ell|_1 = m, |\ell|_\infty = k} 1 \end{aligned}$$

$$\begin{aligned}
&= \sum_{m=0}^{L-1} 2^m \sum_{k=0}^{\infty} |\mathcal{S}(m, k, d)| = \sum_{m=0}^{L-1} 2^m \binom{m+d-1}{d-1} \\
&= \frac{1}{(d-1)!} \left(\sum_{m=0}^{L-1} x^{m+d-1} \right) \Big|_{x=2}^{(d-1)} \\
&= \frac{1}{(d-1)!} \left(x^{d-1} \frac{x^L - 1}{x-1} \right) \Big|_{x=2}^{(d-1)} \\
&= \frac{1}{(d-1)!} \sum_{m=0}^{d-1} \binom{d-1}{m} \cdot (x^{L+d-1} - x^{d-1})^{(m)} \cdot \left(\frac{1}{x-1} \right)^{(d-1-m)} \Big|_{x=2} \\
&= 2^L \sum_{m=0}^{d-1} \binom{L+d-1}{m} (-2)^{d-1-m} + (-1)^d \\
&\sim \frac{2^L L^{d-1}}{(d-1)!} = \frac{1}{(d-1)!} h_L^{-1} |\log_2 h_L|^{d-1}.
\end{aligned}$$

5. Approximability from sparse tensor product spaces

Full tensor-product projector:

$$P_{(0)}^{L,p} = \sum_{|\ell|_{\infty} \leq L} Q_{(0)}^{\ell_1,p} \otimes \cdots \otimes Q_{(0)}^{\ell_d,p} : \bigotimes_{i=1}^d H_{(0)}^1(0,1) \rightarrow V_{(0)}^{L,p}, \quad \ell = (\ell_1, \dots, \ell_d).$$

Sparse tensor-product projector:

$$\hat{P}_{(0)}^{L,p} = \sum_{|\ell|_1 \leq L} Q_{(0)}^{\ell_1,p} \otimes \cdots \otimes Q_{(0)}^{\ell_d,p} : \bigotimes_{i=1}^d H_{(0)}^1(0,1) \rightarrow \hat{V}_{(0)}^{L,p}, \quad \ell = (\ell_1, \dots, \ell_d).$$

Define

$$|u|_{\mathcal{H}^{t+1}(\Omega)} := \max_{s \in \{0,1\}} \max_{1 \leq k \leq d} \left(\max_{\substack{J \subseteq \{1,2,\dots,d\} \\ |J|=k}} |u|_{H^{t+1,s,J}(\Omega)} \right).$$

Theorem

Let $\Omega = (0,1)^d$, $s \in \{0,1\}$, $k \geq 1$, $p \geq 1$ be given. For $1 \leq t \leq \min\{p,k\}$, there exist $\underline{c}_{p,t} > 0$, $\kappa_{(0)}(p,t,s,L) > 0$, independent of d , such that, for any $u \in \mathcal{H}^{k+1}(\Omega)$ and all $L \geq 1$ and $d \geq 2$, we have

$$|u - \hat{P}_{(0)}^{L,p} u|_{\mathbb{H}^s(\Omega)} \leq d^{1+\frac{s}{2}} \underline{c}_{p,t} (\kappa_{(0)}(p,t,s,L))^{d-1+s} 2^{-(t+1-s)L} |u|_{\mathcal{H}^{t+1}(\Omega)}.$$

$$\kappa_{(0)}(p,t,s,L) := \begin{cases} \tilde{c}_{p,0,t}(L+1)e^{1/(L+1)} + \hat{c}_{p,0,(0)}, & s = 0, \\ 2\tilde{c}_{p,0,t} + \hat{c}_{p,0,(0)}, & s = 1. \end{cases}$$

$$\hat{c}_{p,0,(0)} := |Q_{(0)}^{0,p}|_{\mathcal{B}(\mathbb{H}_{(0)}^1(0,1), L^2(0,1))}.$$

The constants

$$\kappa_{(0)}(p, t, s, L) := \begin{cases} \tilde{c}_{p,0,t}(L+1)e^{1/(L+1)} + \hat{c}_{p,0,(0)}, & s = 0, \\ 2\tilde{c}_{p,0,t} + \hat{c}_{p,0,(0)}, & s = 1. \end{cases}$$

For $p \geq 1$, $t \in \mathbb{N}$, $1 \leq t \leq p$, $s \in \{0, 1\}$:

$$\tilde{c}_{p,0,t} = \left(1 + \frac{1}{2^{t+1-s}}\right) \frac{1}{p} \sqrt{\frac{(p-t)!}{(p+t)!}}, \quad \hat{c}_{p,0,(0)} = \frac{1}{\pi}.$$

Refined values for $p = 1$:

$$\tilde{c}_{1,0,1} = \frac{1}{3}, \quad \hat{c}_{1,0,0} = 0.$$

Tracking the constants

Remark (A)

If $\Gamma = \Gamma_0$ (elliptic problem) and $s = 1$ ($H^1(\Omega)$ seminorm error), then

$$\kappa_0(p, p, 1, L) < 1 \quad \forall p \geq 1, \quad L \geq 1.$$

Therefore the factor $(\kappa_0(p, p, 1, L))^{d-1+s}$ decays exponentially as $d \rightarrow \infty$.



M. Griebel (CUP, 2006: Proc. Found. Comp. Math. Santander, Spain, 2005),
 $p = 1, s = 1$, under stronger, $W^{2,\infty}(\Omega)$, regularity on u , for $-\Delta u = f$ with $u|_{\Gamma} = 0$.

Remark (B)

If $s = 0$ (i.e. for $L^2(\Omega)$ norm error), no $|\log_2 h_L|^{d-1}$ term, if

$$p = 2 \text{ and } L \leq 3, \quad p = 3 \text{ and } L \leq 49, \quad p \geq 4 \text{ and } L \leq 528.$$

Remark (C)

If $s = 0$ and

$$\gamma_{(0)}(p, t) := \tilde{c}_{p,0,t} 2^{t+1} / (2^{t+1} - 1) + \hat{c}_{p,0,(0)} < 1,$$

then there exists a positive constant $c_{t,p}$, independent of L and d , such that $\kappa_{(0)}(p, t, 0, L) < 1$ for all $L \geq 1$ and $d \geq 2$ satisfying $L + 1 \leq c_{t,p}(d - 1)$.

If $\Gamma = \Gamma_0$, then $\gamma_0(p, p) < 1$ for all $p \geq 1$. Also,

$$\kappa_0(p, p, 0, L) < 1$$

whenever

$$L + 1 \leq c_{p,p}(d - 1),$$

where

$$c_{1,1} = 0.6, \quad c_{2,2} = 0.71, \quad c_{3,3} = 1.846, \quad c_{4,4} = 2.161, \dots$$

Remark (D)

If $\Gamma_0 \subsetneq \Gamma$ (i.e. hyperbolic boundary $\Gamma_- \cup \Gamma_+ \neq \emptyset$), then

- for $s = 1$, i.e. for $H^1(\Omega)$ seminorm error:

$$\kappa_{(0)}(p, p, 1, L) < 1 \quad \text{when} \quad \begin{cases} p = 2 & \text{and } d \leq 7, \\ p = 3 & \text{and } d \leq 71, \\ p = 4 & \text{and } d \leq 755. \end{cases}$$

- for $s = 0$, i.e. for $L^2(\Omega)$ error, the worst-case scenario is:

$$\kappa_{(0)}(p, p, 0, L) \leq (L+1)^{d-1} \kappa_*^{d-1},$$

where

$$\kappa_* = \frac{1}{L+1} + \frac{2}{p\sqrt{(2p)!}} < 1$$

for $L \geq 1$ and $p \geq 2$.

Technical ingredients of the proof

1. First ingredient: tensorization of seminorms

Proposition

Let $(H_i, \langle \cdot, \cdot \rangle_{H_i})$, $(K_i, \langle \cdot, \cdot \rangle_{K_i})$, $(\tilde{H}_i, \langle \cdot, \cdot \rangle_{\tilde{H}_i})$, $(\tilde{K}_i, \langle \cdot, \cdot \rangle_{\tilde{K}_i})$ for $i = 1, 2$ be separable Hilbert spaces.

Let $T_i \in \mathcal{B}(H_i, K_i)$, $\tilde{T}_i \in \mathcal{B}(\tilde{H}_i, \tilde{K}_i)$ and $Q_i \in \mathcal{B}(H_i, \tilde{H}_i)$ be bounded linear operators, and assume that $\|\tilde{T}_i Q_i v_i\|_{\tilde{K}_i} \leq c_i \|T_i v_i\|_{K_i} \quad \forall v_i \in H_i, i = 1, 2.$

Then

$$\|(\tilde{T}_1 \otimes \tilde{T}_2)(Q_1 \otimes Q_2)u\|_{\tilde{K}_1 \otimes \tilde{K}_2} \leq c_1 c_2 \|(T_1 \otimes T_2)u\|_{K_1 \otimes K_2} \quad \forall u \in H_1 \otimes H_2.$$

In terms of an abbreviated notation:

$$|Q_i|_{(T_i, \tilde{T}_i)} \leq c_i, \quad i = 1, 2 \quad \Rightarrow \quad |Q_1 \otimes Q_2|_{(T_1 \otimes T_2, \tilde{T}_1 \otimes \tilde{T}_2)} \leq c_1 c_2.$$

$$T_i \in \mathcal{B}(H_i, K_i), \tilde{T}_i \in \mathcal{B}(\tilde{H}_i, \tilde{K}_i), Q_i \in \mathcal{B}(H_i, \tilde{H}_i), \quad \|Q_i\|_{T_i, \tilde{T}_i} \leq c_i, \quad i = 1, 2.$$

$$\begin{array}{ccc} H_1 & \xrightarrow{T_1} & K_1 \\ \downarrow Q_1 & & \\ \tilde{H}_1 & \xrightarrow{\tilde{T}_1} & \tilde{K}_1 \end{array} \quad \begin{array}{ccc} H_2 & \xrightarrow{T_2} & K_2 \\ \downarrow Q_2 & & \\ \tilde{H}_2 & \xrightarrow{\tilde{T}_2} & \tilde{K}_2 \end{array}$$

$$\begin{array}{ccc} H_1 \otimes H_2 & \xrightarrow{T_1 \otimes T_2} & K_1 \otimes K_2 \\ \downarrow Q_1 \otimes Q_2 & & \\ \tilde{H}_1 \otimes \tilde{H}_2 & \xrightarrow{\tilde{T}_1 \otimes \tilde{T}_2} & \tilde{K}_1 \otimes \tilde{K}_2 \end{array}$$

$$\|Q_1 \otimes Q_2\|_{T_1 \otimes T_2, \tilde{T}_1 \otimes \tilde{T}_2} \leq c_1 c_2.$$

2. Second ingredient: Explicit bounds on lattice sums

Lemma

Suppose that $d, m \in \mathbb{N}_{>0}$ and $x > 1$. Then,

$$d \cdot x^m \leq \sum_{\ell \in \mathbb{N}^d, |\ell|_1 = m} x^{|\ell|_\infty} \leq d \left(1 + \frac{1}{x-1}\right)^{d-1} \cdot x^m.$$

Lemma

For $L, d \in \mathbb{N}_{>0}$, $\alpha, \beta > 0$, and $x \geq 2$ define

$$A(L, d, x) := \sum_{\substack{\ell \in \mathbb{N}^d \\ |\ell|_1 > L}} x^{-|\ell|_1},$$

$$B(L, d, x, \alpha, \beta) := \sum_{k=1}^d \binom{d}{k} \alpha^k \beta^{d-k} A(L, k, x).$$

Then

$$B(L, d, x, \alpha, \beta) \leq \frac{\alpha e d x}{x-1} \cdot (\alpha(L+1)e^{1/(L+1)} + \beta)^{d-1} \cdot x^{-(L+1)}.$$

Lemma

For $L, d \in \mathbb{N}_{>0}$, $\alpha, \beta > 0$, and $x \geq 2$ define

$$A(L, d, x) := \sum_{\substack{\ell \in \mathbb{N}^d \\ |\ell|_1 > L}} x^{-|\ell|_1},$$

$$B(L, d, x, \alpha, \beta) := \sum_{k=1}^d \binom{d}{k} \alpha^k \beta^{d-k} A(L, k, x).$$

If $\gamma := \alpha \cdot x / (x - 1) + \beta < 1$, then there exists $c_{1,x,\gamma} > 0, c_{2,x,\gamma} \in (0, 1)$ such that

$$\text{whenever } d \geq 2 \quad \text{and} \quad L + 1 \leq c_{1,x,\gamma}(d - 1)$$

we have

$$B(L, d, x, \alpha, \beta) \leq \frac{\alpha dx}{x - 1} \cdot c_{2,x,\gamma}^{d-1} \cdot x^{-(L+1)}.$$

Proof of the Theorem: [$s = 0$]

For $u \in C_{(0)}^\infty(\bar{\Omega}) \subset L^2(\Omega)$, the following identity holds in $L^2(\Omega)$:

$$\begin{aligned} \|u - \hat{P}_{(0)}^{L,p} u\|_{L^2(\Omega)} &\leq \sum_{\ell \in \mathbb{N}^d, |\ell|_1 > L} \left\| \left(\mathcal{Q}_{(0)}^{\ell_1,p} \otimes \cdots \otimes \mathcal{Q}_{(0)}^{\ell_d,p} \right) u \right\|_{L^2(\Omega)} \\ &= \sum_{k=1}^d \sum_{\substack{I \subset \{1,2,\dots,d\} \\ |I|=k}} \sum_{\substack{\ell \in \mathbb{N}^d, |\ell|_1 > L \\ \text{supp}(\ell)=I}} \left\| \left(\mathcal{Q}_{(0)}^{\ell_1,p} \otimes \cdots \otimes \mathcal{Q}_{(0)}^{\ell_d,p} \right) u \right\|_{L^2(\Omega)}. \end{aligned}$$

Now, for any $\ell \in \mathbb{N}^d$ with $I = \text{supp}(\ell)$ and $|I| = k$:

$$\begin{aligned} &\left\| \left(\mathcal{Q}_{(0)}^{\ell_1,p} \otimes \cdots \otimes \mathcal{Q}_{(0)}^{\ell_d,p} \right) u \right\|_{L^2(\Omega)}^2 \\ &\leq \left\{ \prod_{j \in I} |\mathcal{Q}_{(0)}^{\ell_j,p}|_{(\partial^{t+1}, \text{Id}_{L^2(0,1)})}^2 \right\} |\mathcal{Q}_{(0)}^{0,p}|_{(\text{Id}_{\mathbb{H}_{(0)}^1(0,1)}, \text{Id}_{L^2(0,1)})}^{2(d-k)} |u|_{\mathbb{H}^{t+1,0,I}(\Omega)}^2 \\ &= \tilde{c}_{p,0,t}^{2k} \hat{c}_{p,0,(0)}^{2(d-k)} 2^{-2(t+1)|\ell|_1} |u|_{\mathbb{H}^{t+1,0,I}(\Omega)}^2. \end{aligned}$$

Summing this bound over all $I \subseteq \{1, 2, \dots, d\}$ with $|I| = k$ implies

$$\|u - \hat{P}_{(0)}^{L,p} u\|_{L^2(\Omega)} \leq \sum_{k=1}^d \binom{d}{k} \tilde{c}_{p,0,t}^k \hat{c}_{p,0,(0)}^{d-k} \left\{ \sum_{\substack{\ell \in \mathbb{N}^k \\ |\ell|_1 > L}} 2^{-(t+1)|\ell|_1} \right\} \\ \times \max_{1 \leq k \leq d} \left(\max_{\substack{I \subseteq \{1, 2, \dots, d\} \\ |I|=k}} |u|_{\mathbf{H}^{t+1,0,I}(\Omega)} \right).$$

Using the lattice sum lemmas 2 and 3 with $x := 2^{t+1} \geq 2$ for $t \geq 0$, $\alpha := \tilde{c}_{p,0,t}$, and $\beta := \hat{c}_{p,0,(0)}$ we obtain

$$\|u - \hat{P}_{(0)}^{L,p} u\|_{L^2(\Omega)} \leq 2d e \tilde{c}_{p,0,t} \cdot \kappa_{(0)}(p, t, 0, L)^{d-1} \cdot 2^{-(t+1)(L+1)} |u|_{\mathcal{H}^{t+1}(\Omega)}$$

where

$$\kappa_{(0)}(p, t, 0, L) := \tilde{c}_{p,0,t}(L+1)e^{1/(L+1)} + \hat{c}_{p,0,(0)}, \quad p \geq 1, \quad 1 \leq t \leq p, \quad L \geq 1.$$

Hence the required bound for $s = 0$, with $\underline{c}_{p,t} = 2^{-t}e\tilde{c}_{p,0,t}$.

Further, if

$$\Upsilon_{(0)}(t,p) := \tilde{c}_{p,0,t}2^{t+1}/(2^{t+1} - 1) + \hat{c}_{p,0,(0)} < 1,$$

then there exists a constant $c_{t,p} > 0$, independent of L and d , such that $\kappa_{(0)}(p,t,0,L) < 1$ for all $L \geq 1$ and $d \geq 2$ satisfying $L+1 \leq c_{t,p}(d-1)$. \square

6. Stability and convergence of the sparse stabilized FEM

Theorem

Suppose that

$$0 \leq \delta_L \leq \min \left(\frac{h_L^2}{12dp^4|\sqrt{a}|^2}, \frac{1}{c} \right).$$

Then,

$$\forall v_h \in \hat{V}_{(0)}^{L,p} : \quad B_\delta(v_h, v_h) \geq \frac{1}{2} \|v_h\|_{SD}^2.$$

Now, fix

$$\delta_L := K_\delta \cdot \min \left(\frac{h_L^2}{12dp^4|\sqrt{a}|^2}, \frac{h_L}{|b|}, \frac{1}{c} \right),$$

with $K_\delta \in \mathbb{R}_{>0}$ a constant, independent of h_L and d .

Theorem

Let $f \in L^2(\Omega)$, $\Omega = (0, 1)^d$, $u \in \mathcal{H}^{k+1}(\Omega) \cap H^2(\Omega) \cap \bigotimes_{i=1}^d H_{(0)}^1(0, 1)$, $k \geq 1$, and let the stabilization parameter δ_L be as above.

If $p \geq 1$, $1 \leq t \leq \min(p, k)$, $h = h_L = 2^{-L}$ and $L \geq 1$, then

$$\begin{aligned} \| \|u - u_h\| \|_{SD} \leq C_{p,t} d^2 \max\{(2-p)_+, \kappa_{(0)}(p, t, 0, L)^{d-1}, \kappa_{(0)}(p, t, 1, L)^d\} \\ \times \left(|\sqrt{a}| h_L^t + |b|^{\frac{1}{2}} h_L^{t+\frac{1}{2}} + c^{\frac{1}{2}} h_L^{t+1} \right) |u|_{\mathcal{H}^{t+1}(\Omega)}. \end{aligned}$$

Sketch of the proof

Let $h = h_L = 2^{-L}$.

$$\| \|u - u_h\| \|_{\text{SD}} \leq \| \|u - \hat{P}_{(0)}^{L,p} u\| \|_{\text{SD}} + \| \|\hat{P}_{(0)}^{L,p} u - u_h\| \|_{\text{SD}}.$$

The first term on the right is bounded using the approximation Thm from Sec. 5. Further, by coercivity of B_δ on $\hat{V}_{(0)}^{L,p}$ and Galerkin orthogonality,

$$\begin{aligned} \frac{1}{2} \| \|\hat{P}_{(0)}^{L,p} u - u_h\| \|_{\text{SD}}^2 &\leq B_\delta(\hat{P}_{(0)}^{L,p} u - u_h, \hat{P}_{(0)}^{L,p} u - u_h) \\ &= -B_\delta(u - \hat{P}_{(0)}^{L,p} u, \hat{P}_{(0)}^{L,p} u - u_h) \end{aligned}$$

since

$$B_\delta(u - u_h, \hat{P}_{(0)}^{L,p} u - u_h) = 0.$$

Roughly (and not entirely correctly; the precise argument is *much* more involved):

$$\left| B_\delta(u - \hat{P}_{(0)}^{L,p} u, \hat{P}_{(0)}^{L,p} u - u_h) \right| \leq \text{Const.} \| \|u - \hat{P}_{(0)}^{L,p} u\| \|_{\text{SD}} \| \|\hat{P}_{(0)}^{L,p} u - u_h\| \|. \quad \square$$

How about $|u|_{\mathcal{H}^{t+1}(\Omega)}$?

Consider, on $\Omega = (0,1)^d$, the PDE

$$-a : \nabla \nabla u + b \cdot \nabla u + cu = f(x), \quad x \in \Omega,$$

with $f \in L^2(\Omega)$, constant coefficients $a \in \mathbb{R}^{d \times d}$, $b \in \mathbb{R}^d$, and $c \in \mathbb{R}_{>0}$, $a^\top = a \geq 0$, subject to *periodic* boundary conditions.

Recall that

$$|u|_{\mathcal{H}^{t+1}(\Omega)} := \max_{s \in \{0,1\}} \max_{1 \leq k \leq d} \left(\max_{\substack{J \subseteq \{1,2,\dots,d\} \\ |J|=k}} |u|_{\mathbb{H}^{t+1,s,J}(\Omega)} \right).$$

We shall therefore begin by considering, for $s \in \{0,1\}$, $k \in \{1, \dots, d\}$ and $J \subset \{1, \dots, d\}$, with $|J| = k$,

$$|u|_{\mathbb{H}^{t+1,s,J}(\Omega)}.$$

$$u = \sum_{m \in \mathbb{Z}^d} \hat{u}_m e^{2\pi i m \cdot x}, \quad f = \sum_{m \in \mathbb{Z}^d} \hat{f}_m e^{2\pi i m \cdot x}.$$

Substituting these into the PDE yields

$$[m^\top a m + i(b \cdot m) + c] \hat{u}_m = \hat{f}_m \quad \forall m \in \mathbb{Z}^d.$$

Hence,

$$|\hat{u}_m|^2 = \frac{|\hat{f}_m|^2}{(m^\top a m + c)^2 + |b \cdot m|^2} \quad \forall m \in \mathbb{Z}^d.$$

Since $a \geq 0$ and $c > 0$, it follows that

$$|\hat{u}_m|^2 \leq \frac{1}{c^2} |\hat{f}_m|^2 \quad \forall m \in \mathbb{Z}^d.$$

Assume without loss of generality that $J = \{1, \dots, k\}$, where $1 \leq k \leq d$.

Hence,

$$|u|_{\mathbf{H}^{t+1,s,J}(\Omega)}^2 = \sum_{m \in \mathbb{Z}^d} (2m_1\pi)^{2(t+1)} \dots (2m_k\pi)^{2(t+1)} (2m_{k+1})^{2s} \dots (2m_d)^{2s} |\hat{u}_m|^2.$$

Therefore,

$$|u|_{\mathbf{H}^{t+1,s,J}(\Omega)}^2 \leq \frac{1}{c^2} \sum_{m \in \mathbb{Z}^d} (2m_1\pi)^{2(t+1)} \dots (2m_k\pi)^{2(t+1)} (2m_{k+1})^{2s} \dots (2m_d)^{2s} |\hat{f}_m|^2.$$

Equivalently,

$$|u|_{\mathbf{H}^{t+1,s,J}(\Omega)}^2 \leq c^{-2} |f|_{\mathbf{H}^{t+1,s,J}(\Omega)}^2.$$

Therefore,

$$|u|_{\mathcal{H}^{t+1}(\Omega)}^2 \leq c^{-2} |f|_{\mathcal{H}^{t+1}(\Omega)}^2.$$

For example, if $f(x_1, \dots, x_d) = f_1(x_1) \cdots f_d(x_d)$, then

$$|f|_{\mathbf{H}^{t+1,s,J}(\Omega)} = |f_1|_{\mathbf{H}^{t+1}(0,1)} \cdots |f_k|_{\mathbf{H}^{t+1}(0,1)} |f_{k+1}|_{\mathbf{H}^s(0,1)} \cdots |f_d|_{\mathbf{H}^s(0,1)}.$$

Let

$$\alpha_0 = \max_{1 \leq k \leq d} \max_{s \in \{0,1\}} \{|f_k|_{\mathbf{H}^{t+1}(0,1)}, \|f_k\|_{\mathbf{H}^s(0,1)}\}.$$

Then,

$$|f|_{\mathcal{H}^{t+1}(\Omega)} \leq \alpha_0^d,$$

and therefore,

$$|u|_{\mathcal{H}^{t+1}(\Omega)} \leq c^{-1} \alpha_0^d.$$

Example

$$f(x_1, \dots, x_d) = \frac{1}{(2\pi)^{d(t+1)}} \prod_{k=1}^d \sin 2\pi x_k.$$

$$|f|_{\mathcal{H}^{t+1}(\Omega)} \leq 1.$$

Conclusions

- 1 For 2nd-order PDEs with non-negative characteristic form on $\Omega = (0, 1)^d$, we developed a stabilized variational formulation.
- 2 Formulation stable on sparse tensor-product space, of meshwidth $h = h_L$ and polynomial degree $p \geq 1$, independent of:
 - ★ mesh Péclet number;
 - ★ anisotropy in basis functions;
 - ★ degeneracy of elliptic part.
- 3 error analysis shows that the constant decreases exponentially as $d \rightarrow \infty$ (substantially generalizing M. Griebel (2006) from $p = 1$ and Dirichlet b.v.p. for $-\Delta u = f$, to $p > 1$, any sparse basis, and second-order PDEs with non-negative characteristic form).
- 4 We have identified a number of preasymptotic regimes where there is **no** $|\log_2 h_L|^{d-1}$ term in the error bound.

Comments

The statements above presuppose that

$$|u|_{\mathcal{H}^{t+1}(\Omega)} := \max_{s \in \{0,1\}} \max_{1 \leq k \leq d} \left(\max_{\substack{J \subseteq \{1,2,\dots,d\} \\ |J|=k}} |u|_{\mathbf{H}^{t+1,s,J}(\Omega)} \right)$$

is bounded as $d \rightarrow \infty$.

A poorly understood question:

analysis of regularity and growth of norms of solutions of high-dimensional PDEs in spaces of functions with square-integrable mixed derivatives.



H. Yserentant: On the regularity of the electronic Schrödinger equation in Hilbert spaces of mixed derivatives, Numer. Math. (2004).



H. Yserentant: Regularity properties of wavefunctions and the complexity of the quantum-mechanical N -body problem, (2007).