MODELS & MEASURES OF MIXING & EFFECTIVE DIFFUSION

Zhi Lin

Institute for Mathematics & Its Applications University of Minnesota, Minneapolis, MN 55455, USA

KATARÍNA BOĎOVÁ

Department of Applied Mathematics & Statistics Faculty of Mathematics, Physics and Informatics Comenius University, 84248 Bratislava, Slovakia

CHARLES R. DOERING

Department of Mathematics, University of Michigan Ann Arbor, MI 48109-1043, USA

and

Department of Physics and Michigan Center for Theoretical Physics University of Michigan, Ann Arbor, MI 48109-1040, USA

and

Center for the Study of Complex System, University of Michigan Ann Arbor, MI 48109-1107, USA

Big questions:

How can we gauge the effectiveness of a stirrer as a mixer? How might we parameterize stirring as diffusion?

Outline:

- Models
- Conflicts
- Resolution
- More models
- Reconciliation

Mathematical models of mixing

Given flow field $\vec{u}(\vec{x},t)$ with $\nabla \cdot \vec{u} = 0$, consider

Stochastic Diff Eq: $d\vec{X}(t) = \vec{u}(\vec{X},t)dt + \sqrt{2\kappa} d\vec{W}(t)$

- X(t) is passive tracer particle position
- κ is the molecular diffusion coefficient

Advection - Diffusion Eq: $\partial_t \theta + \vec{u} \cdot \nabla \theta = \kappa \Delta \theta + s$

- $\theta(x,t)$ is passive scalar density, concentration
- s(x,t) is passive scalar source-sink distribution
- plus appropriate initial and boundary conditions

Temptation & tradition suggest characterizing stirring as an "effective" diffusion

$$\vec{u} \cdot \nabla - \kappa \Delta \implies -\partial_i K_{ij}^{eff} \partial_j$$

Three questions:

- Which aspects of mixing should be encoded in K^{eff} ?
- Do different criteria produce different K^{eff} ?
- Transferable among applications?

Measure 1:
$$K^{PD} = K_{ij}^{eff}$$

Measure 2:
$$K^{FG} = K_{11}^{eff}$$

Measure 3:
$$\kappa_p^{VR} = \kappa_p^{eff}$$
 for $p = +1, 0, -1$

 $p = +1, 0, -1 \sim$ "small", "intermediate", or "large" scale variance reduction

Measure 1:
$$K^{PD} = K_{ij}^{eff}$$

via tracer particle dispersion

$$\mathbf{E}\left\{\left(X_{i}(t)-X_{i}(0)\right)\left(X_{j}(t)-X_{j}(0)\right)\right\} \sim 2K_{ij}^{eff}t$$

as
$$t \to \infty$$
.

Measure 2: $K^{FG} = K_{11}^{eff}$

via flux - gradient relation, $T = -Gx + \theta \Rightarrow$

$$\partial_t \theta + \vec{u} \cdot \nabla \theta = \kappa \Delta \theta + G(\hat{i} \cdot \vec{u})$$

everything mean zero & periodic on a cell \Rightarrow

$$K_{11}^{eff} = \kappa + \frac{\left\langle u_1 \theta \right\rangle}{G} = \kappa \left(1 + \frac{\left\langle |\vec{\nabla}\theta|^2 \right\rangle}{G^2} \right)$$

Measure 3:
$$\kappa_0^{VR} = \kappa^{eff}$$

via concentration variance reduction

For $s(\vec{x})$ mean 0 and $\partial_t \theta + \vec{u} \cdot \nabla \theta = \kappa \Delta \theta + s(\vec{x})$

$$\kappa^{eff} = \sqrt{\frac{\left\langle \left(\Delta^{-1} s \right)^2 \right\rangle}{\left\langle \theta^2 \right\rangle}}$$

Multiscale Measure 3(a):
$$\kappa_p^{VR} = \kappa_p^{eff}$$

via concentration (inverse) gradient variance reduction

For $s(\vec{x})$ mean 0 and $\partial_t \theta + \vec{u} \cdot \nabla \theta = \kappa \Delta \theta + s(\vec{x})$

$$\kappa_{\pm 1}^{eff} = \sqrt{\frac{\left\langle \left| \nabla^{\pm 1} \Delta^{-1} s \right|^2 \right\rangle}{\left\langle \left| \nabla^{\pm 1} \theta \right|^2 \right\rangle}}$$

Measure 1:
$$K^{PD} = K_{ij}^{eff} \sim \frac{1}{2t} \mathbf{E} \left\{ \left(X_i(t) - X_i(0) \right) \left(X_j(t) - X_j(0) \right) \right\}$$

Measure 2:
$$K^{FG} = K_{11}^{eff} = \kappa \left(1 + \frac{\left\langle |\vec{\nabla}\theta|^2 \right\rangle}{G^2} \right)$$

Measure 3:
$$\kappa_p^{VR} = \kappa_p^{eff} = \sqrt{\frac{\left\langle \left| \nabla^p \Delta^{-1} s \right|^2 \right\rangle}{\left\langle \left| \nabla^p \theta \right|^2 \right\rangle}}$$
 for $p = +1, 0, -1$

Strength of stirring

Dimensionless *Péclet* number : $Pe = \frac{U\ell}{\kappa}$

 $U \sim \text{velocity scale} \quad \dots \quad \ell \sim \text{ length scale}$

Dimensionless *Enhancement* or *Efficacy* factor:

$$E(\text{Pe}) = \frac{\kappa_p^{VR}}{\kappa} \text{ or } \frac{K^{PD,FG}}{\kappa}$$

Fact:

In terms of tracer dispersion or flux-gradient relation, there are flows for which the enhancement may be as large as

$$E(\text{Pe}) = \frac{K^{FG}}{\kappa} \sim \text{Pe}^2 \text{ as } \text{Pe} \to \infty.$$

Fact:

In terms of concentration variance reduction in presence of steady sources & sinks the enhancement cannot be that big.

Theorem:
$$E(\text{Pe}) = \frac{\kappa_p^{VR}}{\kappa} \le \text{Pe}^1 \text{ as } \text{Pe} \to \infty.$$

Resolution

• What length scale ℓ is used in $Pe = U\ell/\kappa$?

In examples where
$$\frac{K^{FG}}{\kappa} \sim \text{Pe}^2$$
 as $\text{Pe} \to \infty$,

$$\operatorname{Pe} = \frac{U\ell_{flow}}{\kappa}.$$

In theorem where
$$E(\text{Pe}) = \frac{\kappa_p^{VR}}{\kappa} \le \text{Pe}^1 \text{ as } \text{Pe} \to \infty,$$

$$\operatorname{Pe} = \frac{U\ell_{source}}{\kappa} = \left(\frac{\ell_{source}}{\ell_{flow}}\right) \times \frac{U\ell_{flow}}{\kappa}.$$

Example: Basic Two-scale Model

A single-scale flow stirring a single-scale source-sink distribution

$$\vec{u}(\vec{x}) = \hat{i} \sqrt{2} U \sin k_u y$$

$$\vec{u}(\vec{x}) = \sqrt{2} S \sin k_s x$$
Two parameters: $Pe = \frac{U}{\kappa k_u}$ and $r = \frac{\ell_{source}}{\ell_{flow}} = \frac{k_u}{k_s}$

Dispersion/Flux-gradient mixing measure

- a.k.a. **Homogenization Theory** (HT) ...
- ... presumably good for $r = k_u/k_s >> 1$:

•
$$\frac{K^{FG}}{\kappa} = 1 + \text{Pe}^2 \implies \text{HT approximation is}$$

$$0 = K^{FG} \frac{d^2 \theta_{\text{HT}}(x)}{dx^2} + s(x) \implies \theta_{\text{HT}}(x) = \frac{\sqrt{2} S \sin k_s x}{\kappa k_u^2 (1 + \text{Pe}^2)}$$

HT appx of
$$\kappa_{p}^{VR} = \sqrt{\frac{\left\langle \left(\Delta^{-1}s\right)^{2}\right\rangle}{\left\langle \theta_{HT}^{2}\right\rangle}} = \sqrt{\frac{\left\langle \left|\nabla^{\pm 1}\Delta^{-1}s\right|^{2}\right\rangle}{\left\langle \left|\nabla^{\pm 1}\theta_{HT}\right|^{2}\right\rangle}} = \kappa(1 + \mathrm{Pe}^{2})$$



Exact solution (for r = 1)



High-Pe (fixed *r*) asymptotic analysis: *Internal-layer theory* (ILT)

$$E_{0} = \kappa_{0} VR / \kappa \sim r^{7/6} \text{ Pe}^{5/6}$$

$$E_{+1} = \kappa_{+1} VR / \kappa \sim r^{1/2} \text{ Pe}^{1/2}$$

$$E_{-1} = \kappa_{-1} VR / \kappa \sim r \text{ Pe}$$















Outline

- Models
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Questions:

- HT fails to predict the scalar variance sustained by steady sources & sinks when Pe > r >> 1. Why?
- Can information about particle dispersion predict variance supression at high Péclet numbers?

• Particle dispersion is time and initial-location dependent ...

$$K_{i,j}^{PD}(t; \vec{X}(0)) = \frac{d}{dt} \frac{1}{2} \mathbf{E} \left\{ \left(X_i(t) - X_i(0) \right) \left(X_j(t) - X_j(0) \right) \right\}$$

• $K^{\text{PD}} \sim \kappa \text{Pe}^2 = \mathcal{O}(\kappa^{-1}) \text{ takes } \mathcal{O}(\ell_{flow}^2/\kappa) \text{ time to develop}$... but $K^{PD}_{i,j}(t; \vec{X}(0)) \sim \kappa + U^2 t$ (at most) for $t \ll \ell^2_{flow}/\kappa$.



More modeling

- Concentration variance for stirred scalars sustained by inhomogeneous sources and sinks is dominated by the "latest" stuff introduced or deleted from the system.
- "Old" particles are relatively well mixed and so don't contribute substantially to the observed variance.
- Variance supression is controlled by particle dispersion rate on relatively *short*, rather than *long*, time scales at high Pe.
- In the presence of sustainted sources & sinks, even as $t \to \infty$ we cannot neglect transient behavior of K^{PD} ...

Dispersion-diffusion theory (DDT)

Given a stirring flow $\boldsymbol{u}(\boldsymbol{x},t)$ and its associated $\mathbf{K}_{ij}^{PD}(t-t_0|\boldsymbol{x}_0,t_0)$, density due to stuff injected at \boldsymbol{x}_0, t_0 may best be described by $\partial_t \rho(\vec{x},t | \vec{x}_0,t_0) = \partial_i K_{ii}^{PD}(t-t_0 | \vec{x}_0,t_0) \partial_i \rho$

$$\lim_{t \downarrow t_0} \rho(\vec{x}, t \mid \vec{x}_0, t_0) = \delta(\vec{x}, t \mid \vec{x}_0)$$

G. K. Batchelor, Diffusion in a field of homogeneous turbulence I. Eulerian analysis, Aust. J. Sci. Res. Series A, Phys. Sci., 2 (1949), 437-450.

Then the total density in presence of sources and sinks is *at best* described by

$$\theta_{\rm DDT}(\vec{x},t) = \int_{-\infty}^{t} dt_0 \int d\vec{x}_0 \rho(\vec{x},t \mid \vec{x}_0,t_0) s(\vec{x}_0,t_0)$$

... which does not satisfy an inhomogeneous diffusion equation!

On a periodic domain $[0,L]^d$

$$\rho(\vec{x},t \mid \vec{x}_0,t_0) = \frac{1}{L^d} \sum_{\vec{k}} \exp\left\{ i\vec{k} \cdot (\vec{x} - \vec{x}_0) - k_i k_j \int_{t_0}^t K_{ij}^{PD}(t'-t_0 \mid \vec{x}_0,t_0) dt' \right\}$$

Note: if
$$K_{ij}^{PD} \sim \left[\kappa + U^2(t - t_0)\right] \delta_{ij}$$
 as $t - t_0 \rightarrow 0$, then

$$\Rightarrow \text{ as } \operatorname{Pe} \rightarrow \infty, \quad \hat{\theta}_{\mathrm{DDT}}(\vec{k}) \sim \frac{\hat{s}(\vec{k})}{kU} \quad \text{ so } \quad \kappa_{0}^{VR} = \sqrt{\frac{\left\langle \left(\Delta^{-1}s\right)^{2}\right\rangle}{\left\langle \theta_{\mathrm{DDT}}^{2}\right\rangle}} \sim U\ell_{source}$$

Reconciliation

- **\$64** question: Is DDT quantitatively accurate?
- For single-scale flow stirring single-scale source ...



More reconciliation

- DDT respects the rigorous bounds on κ_0^{VR} .
- For the single-scale source, the rigorous bound is

 $E(\text{Pe}) = \kappa_0^{\text{VR}} / \kappa \le [1 + r^2 \text{Pe}^2]^{1/2} \sim r \text{Pe} \dots$

... for large *r* or for large Pe!

• Plot *E*(Pe) as a function of (*r*Pe):



Reconciliation, continued

• How does DDT perform for variance supression at large & small scales, i.e., for $\kappa_{\pm 1}^{VR}$?





Density pictures (r = 562)





DDT approximation for κ_0^{VR} is uniformly accurate

Conjecture (potential application)

- Single-scale source, sink & stirring is a special scenario what about *real* turbulent mixing?
- DDT hints how particle dispersion data may predict steady state source-sink sustained variance suppression.
- Homogeneous isotropic turbulence \rightarrow

 $\mathbf{E}[(\mathbf{X}_{i}(t) - \mathbf{X}_{i}(0))(\mathbf{X}_{j}(t) - \mathbf{X}_{j}(0))] = (2\kappa t + U^{2}t^{2} + C_{R}\varepsilon t^{3} + \dots) \delta_{ij}$

... w/turbulent energy dissipation rate per unit mass $\varepsilon \sim U^3/\ell_{flow}$.

On a periodic domain $[0,L]^d$

$$\rho(\vec{x},t \mid \vec{x}_{0},t_{0}) \approx \frac{1}{L^{d}} \sum_{\vec{k}} \exp\left\{ i\vec{k} \cdot (\vec{x}-\vec{x}_{0}) - \frac{1}{2}k^{2} \left[2\kappa(t-t_{0}) + U^{2}(t-t_{0})^{2} + \cdots \right] \right\}$$

$$\theta_{\text{DDT}}(\vec{x},t) = \int_{-\infty}^{t} dt_{0} \int d\vec{x}_{0} \rho(\vec{x},t \mid \vec{x}_{0},t_{0}) s(\vec{x}_{0})$$

$$\downarrow$$

$$\hat{\theta}_{\text{DDT}}(\vec{k}) = \hat{s}(\vec{k}) \int_{0}^{\infty} e^{-\kappa k^{2}\tau - \frac{1}{2}k^{2}U^{2}\tau^{2}} d\tau$$

$$\Rightarrow \text{ as } \operatorname{Pe} = \frac{U\ell_{flow}}{\kappa} \to \infty \text{ at fixed } r = \frac{\ell_{source}}{\ell_{flow}},$$
$$\hat{\theta}_{DDT}(\vec{k}) \sim \frac{\hat{s}(\vec{k})}{k U}$$

Concrete conjecture:

Does Statistically Homogeneous

Isotropic Turbulence saturate

the upper bound on E(Pe)?

$$\kappa^{eff}$$
 approximated by $\kappa_{0}^{VR} = \sqrt{\frac{\left\langle \left(\Delta^{-1}s\right)^{2}\right\rangle}{\left\langle \theta_{DDT}^{2}\right\rangle}} \sim \kappa r \operatorname{Pe} \quad \boldsymbol{\swarrow}$

$$= \left(\frac{\boldsymbol{\ell}_{source}}{\boldsymbol{\ell}_{flow}}\right) U \boldsymbol{\ell}_{flow}$$

with
$$\boldsymbol{\ell}_{source} = \left(\frac{\left\langle \left(\Delta^{-1}s\right)^{2}\right\rangle}{\left\langle \left(\Delta^{-1/2}s\right)^{2}\right\rangle}\right)^{1/2}$$

i.e., "mixing length" ~ ℓ_{source}

$$\Rightarrow \text{ as } \operatorname{Pe} = \frac{U\ell_{flow}}{\kappa} \to \infty \text{ at fixed } r = \frac{\ell_{source}}{\ell_{flow}},$$
$$\hat{\theta}_{DDT}(\vec{k}) \sim \frac{\hat{s}(\vec{k})}{k U}$$

Source Distribution



DDT Turbulence



Regular Diffusion



Last words

- Different definitions of effective diffusion may indeed yield different effective diffusivities.
- We cannot generally use long-time transient dispersion results for source-sink problems.
- There may not be an effective diffusion equation to describe source-sink stirring.
- Flux-gradient model does not contain all the relevant information for source-sink stirring.
- Transient mixing and source-sink stirring are *different phenomena* using *different features* of the flow:

Scalar source-sink stirring is all about *transport*



THE END